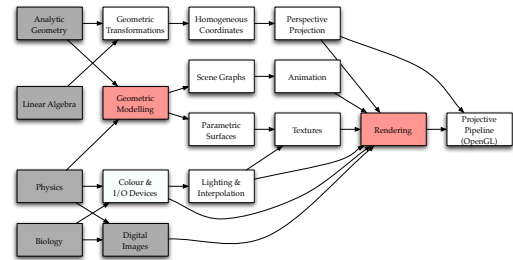


Geometry in 3 Dimensions

COMP 3003
Autumn 2005

Where We Are



Rendering

- *Rendering* converts *maths* to *images*
 - we can choose how we do it
 - *two* basic methods:
 - *vector* graphics - abstract description
 - *raster* graphics - concrete image

Vector vs. Raster

- Vector is better:
 - when you need a *high-level* description
- Raster is better:
 - if you are designing hardware
- Geometric modelling is *vector* graphics
 - OpenGL converts it to *raster* graphics

Vector Graphics

- Are a set of instructions for drawing:
 - Move 1.0 mm left, 2.0 mm down
 - Take a red HB pencil 1 mm wide at tip
 - Draw at angle of 72° for 3 mm
- Example: Postscript, PDF, Illustrator
 - but printer is usually *raster* anyway

Raster Graphics

- Treat image as a large 2-D array of *pixels*
- Almost ubiquitous now (why?)
- This is what we have used so far
 - But it takes a *lot* of pixels
 - Less *compact* than vector graphics
 - And it's harder to change the image

Geometric Modelling

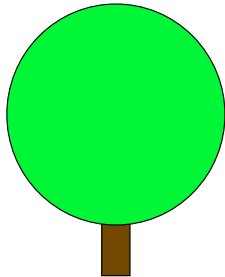
- We need to describe the world
- Most important:
 - where an object is
 - what it is
 - how it behaves

A tree



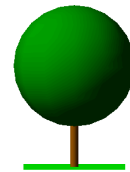
How can we describe this object?

Drawing a Tree



Draw a circle on top of a rectangle

Drawing a 3D Tree



Draw a sphere on top of a cylinder

Complex Geometry

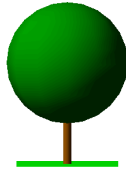
- This isn't a very good tree
- It's too simple geometrically
- A real tree has ?100,000? leaves
- But for now, let's pretend it's OK

Geometric Description

- How to describe a large complex object:
 - break into smaller *primitives*
 - spheres, cylinders, boxes
 - polygons, polyhedra, prisms
 - render each primitive separately

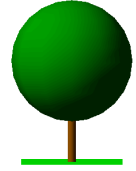
Description

- Draw a sphere
 - radius 10 m
 - centred 7 m above ground
 - colour light green
- Draw a cylinder
 - radius 2 m, height 15 m
 - bottom face on ground
 - colour brown

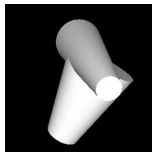


CSG: Constructive Solid Geometry

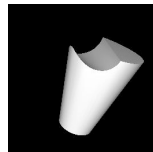
- Tree is built of smaller objects
- Formally, the *union* of them
- Can also do things like:
 - *subtract* objects
 - *xor* objects
- But not with OpenGL



CSG Example



Union



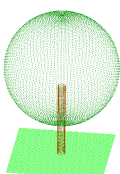
Subtraction

<http://www.cs.unc.edu/~geom/CSG/boole.html>

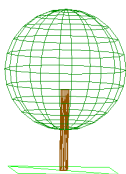
Rendering Methods

- We don't have to render *realistically*
- Sometimes better to retain abstraction
 - *point clouds*
 - *wireframe*
 - *flat shaded surfaces*
 - *smooth shaded surfaces*

Styles of Rendering



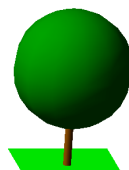
Points



Wireframe
(Lines)



Faceted
(Flat)



Smooth

Building Objects

- Objects are *built up* from primitives
 - points, lines, triangles
- We will build the following:
 - *Platonic* solids
 - *Solids* of revolution

OpenGL commands

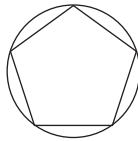
- `glVertex3f(x,y,z);`
 - specifies a vertex with 3 floats
- `glBegin(GL_LINES);`
 - starts drawing lines (2 points each)
- `glEnd();`
 - ends a group of vertices

Polygons

- A *polygon* is a 2-D shape
 - triangle (3 sides)
 - square / rectangle / quadrilateral (4)
 - pentagon (5)
 - hexagon (6)
 - circle (∞)

Regular Pentagon

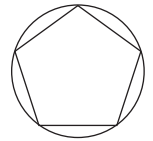
- 5 vertices on a circle
- spaced $360/5 = 72^\circ$ apart
- Edges (lines) between them



```
glBegin(GL_LINES);
for (vertex = 0; vertex < 5; vertex++)
{ // vertex loop
  theta1 = vertex * 72 / 360 * 2 * PI; // in radians
  theta2 = (vertex + 1) * 72 / 360 * 2 * PI;
  glVertex3f(sin(theta1), cos(theta1), 0.0);
  glVertex3f(sin(theta2), cos(theta2), 0.0);
} // vertex loop
glEnd();
```

Regular n -gon

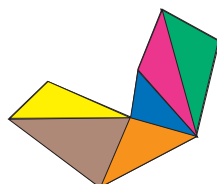
- n vertices on a circle
- spaced $360/n = 72^\circ$ apart
- Edges (lines) between them



```
glBegin(GL_LINES);
for (vertex = 0; vertex < n; vertex++)
{ // vertex loop
  theta1 = vertex * 2 * PI / n; // in radians
  theta2 = (vertex + 1) * 2 * PI / n;
  glVertex3f(sin(theta1), cos(theta1), 0.0);
  glVertex3f(sin(theta2), cos(theta2), 0.0);
} // vertex loop
glEnd();
```

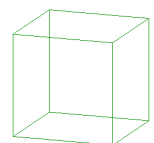
Filling Polygons

- Last week we *rasterized* triangles
 - i.e. we drew *filled* triangles
- Any polygon can be turned into triangles
 - by cutting vertices off



Polyhedra

- A *polyhedron* is a 3-D shape
 - of *vertices*
 - connected with *edges*
- Can be rendered as lines
 - this is called *wireframe*



Example: A Cube

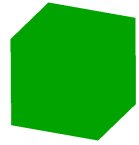
```
glBegin(GL_LINES);
glVertex3f(-1.0, -1.0, -1.0); glVertex3f(-1.0, -1.0, 1.0);
glVertex3f(-1.0, -1.0, 1.0); glVertex3f(-1.0, 1.0, 1.0);
glVertex3f(-1.0, 1.0, 1.0); glVertex3f(-1.0, 1.0, -1.0);
glVertex3f(-1.0, 1.0, -1.0); glVertex3f(-1.0, -1.0, -1.0);

glVertex3f(-1.0, -1.0, -1.0); glVertex3f(1.0, -1.0, -1.0);
glVertex3f(-1.0, -1.0, 1.0); glVertex3f(1.0, -1.0, 1.0);
glVertex3f(-1.0, 1.0, 1.0); glVertex3f(1.0, 1.0, 1.0);
glVertex3f(-1.0, 1.0, -1.0); glVertex3f(1.0, 1.0, -1.0);

glVertex3f(1.0, -1.0, -1.0); glVertex3f(1.0, -1.0, 1.0);
glVertex3f(1.0, -1.0, 1.0); glVertex3f(1.0, 1.0, 1.0);
glVertex3f(1.0, 1.0, 1.0); glVertex3f(1.0, 1.0, -1.0);
glVertex3f(1.0, 1.0, -1.0); glVertex3f(1.0, -1.0, -1.0);
glEnd();
```

Solid Polyhedra

- Polyhedra also have *surfaces*
 - each *face* is a polygon
 - broken into triangles
 - specified in CCW order
 - from the outside



Example: A Cube

```
GLuint vertices[8][3] =
{
    -1, -1, -1,  -1, -1, 1,  -1, 1, -1,  -1, 1, 1,
    1, -1, -1,  1, -1, 1,  1, 1, -1,  1, 1, 1};

glBegin(GL_TRIANGLES);

glVertex3iv(vertices[0]); glVertex3iv(vertices[1]); glVertex3iv(vertices[3]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[3]); glVertex3iv(vertices[2]);

glVertex3iv(vertices[0]); glVertex3iv(vertices[4]); glVertex3iv(vertices[5]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[5]); glVertex3iv(vertices[4]);

glVertex3iv(vertices[0]); glVertex3iv(vertices[2]); glVertex3iv(vertices[6]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[6]); glVertex3iv(vertices[4]);

glVertex3iv(vertices[7]); glVertex3iv(vertices[4]); glVertex3iv(vertices[6]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[5]); glVertex3iv(vertices[4]);

glVertex3iv(vertices[0]); glVertex3iv(vertices[2]); glVertex3iv(vertices[3]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[6]); glVertex3iv(vertices[2]);

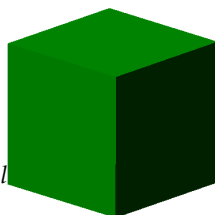
glVertex3iv(vertices[0]); glVertex3iv(vertices[1]); glVertex3iv(vertices[5]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[3]); glVertex3iv(vertices[1]);
glEnd();
```

Lighting & Shading

- We perceive 3-D objects using *shading*
 - cues to the visual system
 - based on amount of light reflected
 - this depends on the *angle* of reflection
 - which depends on the *surface normal*

Shaded Polyhedra

- Each *face* lies on a plane
 - we can compute a *normal*
 - for reflecting light
- Specify normal with *glNormal*
 - *before* specifying vertices



Example: A Cube

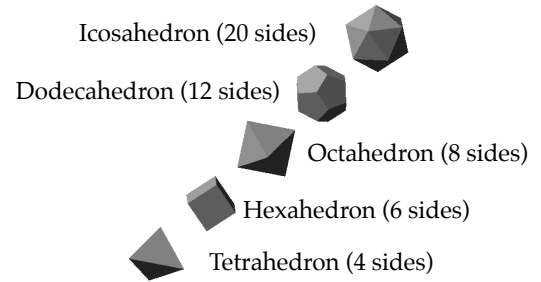
```
GLuint vertices[8][3] =
{
    -1, -1, -1,  -1, -1, 1,  -1, 1, -1,  -1, 1, 1,
    1, -1, -1,  1, -1, 1,  1, 1, -1,  1, 1, 1};

glBegin(GL_TRIANGLES);
glNormal3i(-1, 0, 0); //face 2
glVertex3iv(vertices[0]); glVertex3iv(vertices[2]); glVertex3iv(vertices[3]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[3]); glVertex3iv(vertices[1]);
glNormal3i(0, -1, 0); //face0
glVertex3iv(vertices[0]); glVertex3iv(vertices[1]); glVertex3iv(vertices[5]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[5]); glVertex3iv(vertices[4]);
glNormal3i(0, 0, -1); //face1
glVertex3iv(vertices[0]); glVertex3iv(vertices[4]); glVertex3iv(vertices[6]);
glVertex3iv(vertices[0]); glVertex3iv(vertices[6]); glVertex3iv(vertices[2]);
glNormal3i(1, 0, 0); //face3
glVertex3iv(vertices[6]); glVertex3iv(vertices[5]); glVertex3iv(vertices[4]);
glVertex3iv(vertices[6]); glVertex3iv(vertices[5]); glVertex3iv(vertices[7]);
glNormal3i(0, 1, 0); //face5
glVertex3iv(vertices[6]); glVertex3iv(vertices[3]); glVertex3iv(vertices[7]);
glVertex3iv(vertices[6]); glVertex3iv(vertices[3]); glVertex3iv(vertices[2]);
glNormal3i(0, 0, 1); //face4
glVertex3iv(vertices[5]); glVertex3iv(vertices[3]); glVertex3iv(vertices[1]);
glVertex3iv(vertices[5]); glVertex3iv(vertices[3]); glVertex3iv(vertices[7]);
glEnd();
```

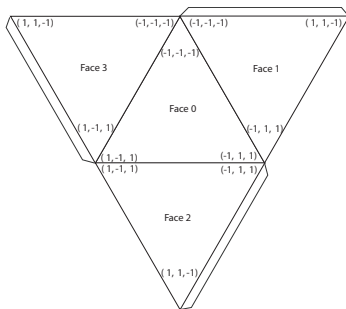
Platonic Solids

- Regular *convex* polyhedra
- All faces are same size and shape
- Each face is a regular polygon
- Each edge is same length
- Convex = no indentations

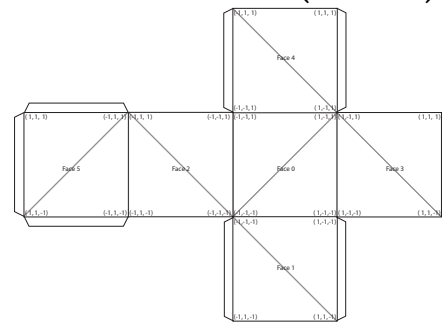
5 Platonic Solids



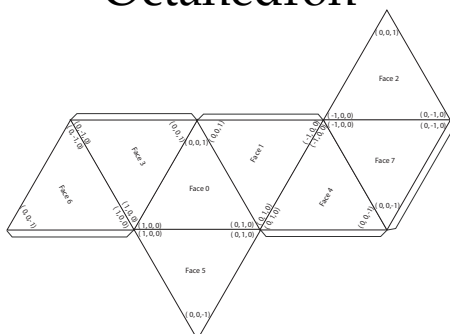
Tetrahedron



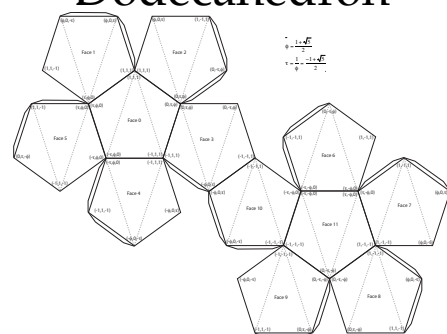
Hexahedron (Cube)



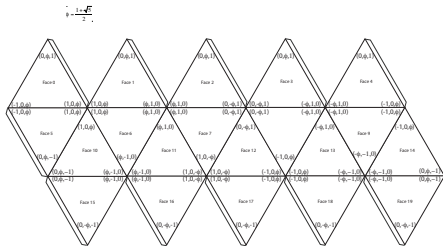
Octahedron



Dodecahedron



Icosahedron



Round Objects

- We *approximate* round objects
- with polyhedra
- possibly with *lots* of faces
- How can we approximate a cylinder?
- as an *extruded* polygon
- turn each edge into a vertical strip

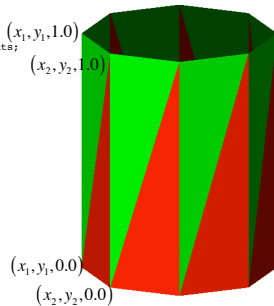
A Vertical Cylinder

```
for (float i = 0.0; i < nSegments; i += 1.0)
{ /* a loop around circumference of a tube */
float angle = PI * i * 2.0 / nSegments;
float nextAngle = PI * (i + 1.0) * 2.0 / nSegments;

/* compute sin & cosine */
float x1 = sin(angle), y1 = cos(angle);
float x2 = sin(nextAngle), y2 = cos(nextAngle);

/* draw top (green) triangle */
glVertex3f(x1, y1, 1.0);
glVertex3f(x2, y2, 1.0);
glVertex3f(x1, y1, 1.0);

/* draw bottom (red) triangle */
glVertex3f(x1, y1, 0.0);
glVertex3f(x2, y2, 0.0);
glVertex3f(x1, y1, 0.0);
} /* a loop around circumference of a tube */
```



Smoother Cylinders

- How can we make the cylinder *smoother*?
- provide normals for *each* vertex
- based on the *tangent plane*
- Cylinder is vertical, so normal is horizontal
- sticking straight out through each vertex

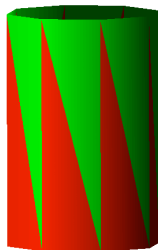
A Smoother Cylinder

```
for (float i = 0.0; i < nSegments; i += 1.0)
{ /* a loop around circumference of a tube */
float angle = PI * i * 2.0 / nSegments;
float nextAngle = PI * (i + 1.0) * 2.0 / nSegments;

/* compute sin & cosine */
float x1 = sin(angle), y1 = cos(angle);
float x2 = sin(nextAngle), y2 = cos(nextAngle);

/* draw top (green) triangle */
glNormal3f(x1, y1, 0.0); glVertex3f(x1, y1, 1.0);
glNormal3f(x2, y2, 0.0); glVertex3f(x2, y2, 1.0);
glNormal3f(x1, y1, 0.0); glVertex3f(x1, y1, 1.0);

/* draw bottom (red) triangle */
glNormal3f(x1, y1, 0.0); glVertex3f(x1, y1, 0.0);
glNormal3f(x2, y2, 0.0); glVertex3f(x2, y2, 0.0);
glNormal3f(x1, y1, 0.0); glVertex3f(x1, y1, 0.0);
} /* a loop around circumference of a tube */
```



Some Round Objects

